To do something else

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The three fundamental normative notions, *prohibition*, *permission* and *obligation*, can be defined in terms of the consequences of doing actions.

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The three fundamental normative notions, *prohibition*, *permission* and *obligation*, can be defined in terms of the consequences of doing actions.

Anderson [1967] and Kanger [1971] followed this idea and independently developed a deontic logic. This is a classical modal logic and it leads to quite many problems.

Starting from the same idea, Meyer [1988] proposed a deontic logic based on a fragment of PDL.

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This work applies deontic operators to actions and many problems with previous deontic logics are avoided.

Meyer's work does not handle the normative notions very well, as the following statements are satisfiable in it:

- Killing the president is not allowed, but killing him and then surrendering to the police is.
- Rescuing the injured and then calling an ambulance is obligated, but rescuing the injured is not.

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Its formalization of refraining to do something is not reasonable:

- The intersection of α and α is not always empty. This means that there may be ways to refrain from α while at the same time doing α.
- The intersection of α and α; β is not always empty. This means that performing α; β may be a way to refrain from doing α.

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Let *a* and *b* be two different atomic actions. Fix a start point. When would we say that the agent has done something else than *a*; *b*?

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Clearly if the agent has done a, he has done something else than b. Then if he has done a; b, he has done something else than b. Then if he has done b, he has done something else than a; b.

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Clearly if the agent has done a, he has done something else than b. Then if he has done a; b, he has done something else than b. Then if he has done b, he has done something else than a; b.

We can not say that if the agent has done a, he has done something else than a; b, otherwise we have to say that if he has done a; b, he has done something else than a; b.

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An action is *permitted* at a state if the state will always be fine during some performance of this action.

An action is *obligated* at a state if the state will be bad at some point during any performance of *anything else*.

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$$\begin{array}{l} \alpha ::= a \mid 0 \mid (\alpha; \alpha) \mid (\alpha \cup \alpha) \mid \alpha^* \\ \phi ::= p \mid \top \mid \mathfrak{b} \mid \neg \phi \mid (\phi \land \phi) \mid \|\alpha\|\phi \end{array}$$

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 $\|\alpha\|\phi$ means that for any way to perform α , ϕ will be the case at some point in the process.

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The dual $\langle\!\langle \alpha \rangle\!\rangle \phi$ of $\|\alpha\|\phi$ says that there is a way to perform α s.t. ϕ will be the case at all the points in the process.

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 $F\alpha$, α is *forbidden*, is defined as $\|\alpha\|\mathfrak{b}$. $P\alpha$, α is *permitted*, is defined as $\langle\!\langle \alpha \rangle\!\rangle \neg \mathfrak{b}$.

 $\mathfrak{M} = (W, \{R_a \mid a \in \Pi_0\}, B, V) \text{ is a model where }$

- *W* is a nonempty set of states
- for any $a \in \Pi_0$, $R_a \subseteq W \times W$, and for any $a, b \in \Pi_0$, $R_a \cap R_b = \emptyset$

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- $\blacksquare B \subseteq W$
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Roughly a model is a labeled transion system plus a set of bad states.

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Each finite sequence of states is called a trace. Each action α corresponds to a set S_α of traces.

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 $\mathfrak{M}, w \Vdash \phi, \phi$ being true at w in \mathfrak{M} , is defined as follows:

- $\blacksquare \mathfrak{M}, w \Vdash \mathfrak{b} \Leftrightarrow w \in B$
- $\mathfrak{M}, w \Vdash F\alpha \Leftrightarrow$ for any trace $w_0 \ldots w_n$, if $w_0 = w$ and $w_0 \ldots w_n \in S_\alpha$, then $\mathfrak{M}, w_i \Vdash \mathfrak{b}$ for some $i \leq n$ s.t. $1 \leq i \leq n$
- $\mathfrak{M}, w \Vdash P\alpha \Leftrightarrow$ there is a trace $w_0 \ldots w_n$ s.t. $w_0 = w, w_0 \ldots w_n \in S_\alpha$ and $\mathfrak{M}, w_i \Vdash \neg \mathfrak{b}$ for any $i \leq n$ s.t. $1 \leq i \leq n$

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A computation sequence, called a *seq*, is a sequence of atomic actions. An example: *abab* is a seq.

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Each action α corresponds to a set $CS(\alpha)$ of seqs.

$$\square CS(a;b) = \{ab\}$$

•
$$CS((a;b) \cup (c;d)) = \{ab, cd\}$$

$$\square CS(a^*) = \{\epsilon, a, aa, \dots\}$$

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An example: *b* is *x*-different from *ab*, but *a* is not *x*-different from *ab*.

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For any actions α and β , α is *x*-different from β , $\alpha \notin \beta$, if for any seqs $\sigma \in CS(\alpha)$ and $\tau \in CS(\beta)$, $\sigma \notin \tau$.

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The relation of *x*-different formalizes the word "else" in the imperatives such as "don't watch cartoon and do something else". If α is *x*-different from β , then doing α is doing something else from β .

For an action α , there might be many actions each of which is something else. The relation of *x*-different itself is not enough to handle the notion of to do something else, as the latter also involves a quantifier over actions.

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Luckily, for any α , among the actions which are something else, there is a *greatest* one in the sense that it is the union of all of them. This lets us deal with the notion of to do something else without introducing any quantifier over actions.

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Proposition

For any α , there is a β s.t. $CS(\beta) = \widetilde{CS(\alpha)}$.



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 β is called the *opposite* of α , denoted as $\widetilde{\alpha}$. An example: let $\Pi_0 = \{a, b\}$; then $\widetilde{a} = b$; $(a \cup b)^*$.

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Proposition

 $CS(\widetilde{\alpha}) = \bigcup \{ CS(\beta) \, | \, \beta \not \approx \alpha \}.$

 $\tilde{\alpha}$ is the union of all the actions *x*-different from α . To refrain to do α is to do something else; to do *anything else* is to do $\tilde{\alpha}$.

 $O\alpha$, α is *obligatory*, is defined as $\|\tilde{\alpha}\|_{\mathfrak{b}}$; it means that no matter what else except α to do and how to do it, the state will be bad at some point in the process.

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 $\mathfrak{M}, w \Vdash O\alpha \Leftrightarrow$ for any trace $w_0 \dots w_n$, if $w_0 = w$ and $w_0 \dots w_n \in S_{\widetilde{\alpha}}$, then $w_i \Vdash \mathfrak{b}$ for some $i \leq n$

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A test ϕ ? in trace semantics is a set of states in which ϕ is true. Trivially $F(\phi$?) is never true and $P(\phi$?) is always true. This means that there is no restriction on testing and testing is always free.

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Let C be the set of concise sets of seqs. Is there a known algebra related with $(C, \otimes, \cup, {}^*, \tilde{})$?

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How do we dynamize it?

What is the computational complexity of it?

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Instead of the division of good and evil states, we want to introduce the more fine-grained notion of *betterness* in further work.

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Thanks!

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