# Uniform Interpolantion in Multi-Agent Modal Logics

#### Liangda Fang, Yongmei Liu and Hans van Ditmarsch

Dept. of Computer Science Jinan University

May 21, 2016

Accepted at the IJCAI-2016



Introduction	Preliminaries	Uniform interpolation	Conclusions and future work
Introduction			

- $\mathcal{P}$ : a finite set of propositions;
- $p \in \mathcal{P}$ ;
- $\varphi$ : the original formula;
- $\psi$ : a uniform interpolant of  $\varphi$  on  $\bar{p}$  ( $\mathcal{P} \setminus p$ ) satisfies the following properties:
  - $\psi$  uses  $var(\varphi)$  without p;
  - $\varphi \models \psi$ ;
  - For any query  $\eta$  which does not contain  $p,\,\varphi\models\eta$  iff  $\psi\models\eta.$

How to compute  $\psi$ ?

Introduction

# A brute-force approach to propositional logic

- Transform  $\varphi$  into an equivalent principal DNF  $\psi$ (a disjunction of full terms using propositions occurred in  $\varphi$ );
- Obtain ψ<sup>p</sup> by eliminating any occurrence of p or ¬p, or replacing any occurrence of p or ¬p with ⊤ in ψ.



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Introduction

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   (a disjunction of full terms using propositions occurred in φ);
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#### Example

• 
$$\varphi = p \wedge q \vee \neg p \wedge \neg r;$$

• 
$$\psi = (p \wedge q \wedge r) \vee (p \wedge q \wedge \neg r) \vee (\neg p \wedge q \wedge \neg r) \vee (\neg p \wedge \neg q \wedge \neg r);$$

• 
$$\psi^p = (q \wedge r) \lor (q \wedge \neg r) \lor (\neg q \wedge \neg r).$$



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Introduction

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#### Example

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$$\varphi = p \wedge q \vee \neg p \wedge \neg r;$$

• 
$$\psi = (\mathbf{p} \land q \land r) \lor (\mathbf{p} \land q \land \neg r) \lor (\neg \mathbf{p} \land q \land \neg r) \lor (\neg \mathbf{p} \land q \land \neg r);$$

• 
$$\psi^p = (q \wedge r) \lor (q \wedge \neg r) \lor (\neg q \wedge \neg r).$$

# How about multi-agent modal logics?

- Modal logic: propositional logic +  $\mathbf{K}_i$  operators;
- $\mathbf{K}_i \varphi$ : agent *i* knows  $\varphi$ .



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# Outline





3 Uniform interpolation





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# Outline





- 3 Uniform interpolation
- ④ Conclusions and future work



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# Modal language: $\mathcal{L}_{\mathbf{C}}^{\mathbf{K}}$

# Definition (Syntax of $\mathcal{L}_{\mathbf{C}}^{\mathbf{K}}$ )

$$\varphi ::= p \mid \neg \varphi \mid \varphi \land \varphi \mid \mathbf{K}_i \varphi \mid \mathbf{C} \varphi,$$

where  $p \in \mathcal{P}$ ,  $i \in \mathcal{A}$ , and  $\varphi \in \mathcal{L}_{\mathbf{C}}^{\mathbf{K}}$ .



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# Definition (Two sublanguages)

- $\mathcal{L}_n^{\mathbf{K}}$ :  $\mathcal{L}_{\mathbf{C}}^{\mathbf{K}}$  without  $\mathbf{C}$  operator;
- **2**  $\mathcal{L}_{\mathbf{PC}}^{\mathbf{K}}$ :  $\mathcal{L}_{\mathbf{C}}^{\mathbf{K}}$  with propositional common knowledge, *i.e.*, any  $\varphi$  appearing in  $\mathbf{C}\varphi$  must be propositional.



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11	ntroduction	Preliminaries	Uniform Interpolation	Conclusions and future work
Kr	ipke models	5		
	Definition (	Kripke mode	ls)	
	A Kripke model is a tuple $\langle S,R,V angle$ where			
	• S: a nor	n-empty set o	f states,	

- R: for each  $i \in \mathcal{A}$ ,  $R_i \subseteq S \times S$  is a relation on states.
- $V\colon\,S\to 2^{\mathcal{P}}$  is a function assigning to each proposition in a subset of states.
- A pair (M, s) is called a pointed model.



Introduction	Preliminaries	Uniform interpolation	Conclusions and future work
Kripke mo	dels		
Definitio			
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- A Kripke model is a tuple ⟨S, R, V⟩ where
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- A pair  $\left(M,s\right)$  is called a pointed model.

Logic systems	Restrictions on $R$	
K	no restrictions	
D	Seriality	
Т	Reflexivity	
K45	Transitivity + Euclidean	
KD45	KD45 Seriality + Transitivity + Euclidean	
S5	Reflexivity + Euclidean	



# Cover modalites

## Definition (Cover modalities)

$$\mathbf{2} \ \nabla \Phi = \mathbf{C}(\bigvee_{\varphi \in \Phi} \varphi) \land \bigwedge_{\varphi \in \Phi} \hat{\mathbf{C}} \varphi.$$

We can use  $\nabla_i$  (resp.  $\nabla$ ) modality instead of  $\mathbf{K}_i$  (resp. C) modality.



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# Canonical formulas

#### Definition (Canonical formulas)

Let  $P \subseteq \mathcal{P}$  be finite. We inductively define the set  $E_k^P$  as follows: •  $E_0^P = \{ \bigwedge_{p \in \mathcal{X}} p \land \bigwedge_{p \in P \setminus \mathcal{X}} \neg p \mid \mathcal{X} \subseteq P \};$ •  $E_{k+1}^P = \{ \delta_0 \land \bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i \mid \delta_0 \in E_0^P \text{ and } \Phi_i \subseteq E_k^P \}.$   $\delta_k \in E_k:$  completely characterizes a Kripke model up to depth ka full terms in modal logics.



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 $\delta_k \in E_k: \text{ completely characterizes a Kripke model up to depth } k$  a full terms in modal logics.

#### Proposition

Any formula in  $\mathcal{L}_n^{\mathbf{K}}$  can be equivalently transformed into a disjunction of satisfiable canonical formulas.

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# Canonical formulas



Figure: Kripke model



# Outline



2 Preliminaries

- 3 Uniform interpolation
- ④ Conclusions and future work



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# Computation of uniform interpolants

- Obtain δ<sup>p</sup> by eliminating any occurrence of p or ¬p, or replacing any occurrence of p or ¬p with ⊤ in δ;



# Computation of uniform interpolants

- Obtain δ<sup>p</sup> by eliminating any occurrence of p or ¬p, or replacing any occurrence of p or ¬p with ⊤ in δ;
- $\ \, { \bigcirc } \ \, \bigvee_{\delta\in\Phi} \delta^p \ \, \text{is a uniform interpolation of } \varphi \ \, \text{on } \bar p.$

#### Example

•  $\varphi = \hat{\mathbf{K}}_i p \wedge \hat{\mathbf{K}}_i \neg p;$ •  $\varphi \equiv \delta_1 \vee \delta_2;$ •  $\delta_1 = p \wedge \nabla_i \{p, \neg p\};$ •  $\delta_2 = \neg p \wedge \nabla_i \{p, \neg p\};$ •  $\delta_1^p \vee \delta_2^p \equiv \top \wedge \nabla_i \{\top\} \equiv \hat{\mathbf{K}}_i \top.$ 

#### Theorem

Let L be K<sub>n</sub>, D<sub>n</sub>, T<sub>n</sub>, K45<sub>n</sub>, KD45<sub>n</sub> or S5<sub>n</sub>. Let  $\delta$  be a pc-canonical formula satisfiable in L. Then,  $\delta^p$  is a uniform interpolant of  $\delta$  on  $\bar{p}$ .



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#### Theorem

Let L be  $K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  or  $S5_n$ . Let  $\delta$  be a pc-canonical formula satisfiable in L. Then,  $\delta^p$  is a uniform interpolant of  $\delta$  on  $\bar{p}$ .

# Definition (Uniform interpolation)

A logic L has uniform interpolation: for any L-formula  $\varphi$  and any proposition p, there exists an L-formula  $\psi$  which is a uniform interpolant of  $\varphi$  on  $\bar{p}$ .



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A logic L has uniform interpolation: for any L-formula  $\varphi$  and any proposition p, there exists an L-formula  $\psi$  which is a uniform interpolant of  $\varphi$  on  $\bar{p}$ .

#### Corollary

 $K_n$ ,  $D_n$ ,  $T_n$ ,  $K45_n$ ,  $KD45_n$  and  $S5_n$  have uniform interpolation.



# Common knowledge case

- Negative result: KC does not have uniform interpolation. [Studer, 2009]
- We consider the propositional common knowledge case, *i.e.*,  $\mathcal{L}_{\mathbf{PC}}^{\mathbf{K}}$  where any  $\varphi$  appearing in  $\mathbf{C}\varphi$  must be propositional.



# Pc-canonical formulas

# Definition (Pc-canonical formulas)

Let  $P \subseteq \mathcal{P}$  be finite. We inductively define the set  $C_k^P$  as follows:

• 
$$C_0^P = \{\theta \land \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P\};$$

• 
$$C_{k+1}^P = \{\theta \land (\bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i) \land \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P, \Phi_i \subseteq C_k^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P \}.$$



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• 
$$C_{k+1}^P = \{\theta \land (\bigwedge_{i \in \mathcal{A}} \nabla_i \Phi_i) \land \nabla \Phi_{\mathcal{A}} \mid \theta \in E_0^P, \Phi_i \subseteq C_k^P \text{ and } \Phi_{\mathcal{A}} \subseteq E_0^P \}.$$

#### Proposition

Any formula in  $\mathcal{L}_{PC}^{K}$  can be equivalently transformed into a disjunction of satisfiable pc-canonical formulas.



#### Theorem

Let L be KC, DC, TC, K45C, KD45C or S5C. Let  $\delta$  be a pc-canonical formula satisfiable in L. Then,  $\delta^p$  is a uniform interpolant of  $\delta$  on  $\bar{p}$ .

#### Corollary

KPC, DPC, TPC, K45PC, KD45PC and S5PC have uniform interpolation.



# Conclusions

- Prove that K<sub>n</sub>, D<sub>n</sub>, T<sub>n</sub>, K45<sub>n</sub>, KD45<sub>n</sub> and S5<sub>n</sub> have uniform interpolation.
- Extend the above results to propositional common knowledge case.



Liangda Fang, Yongmei Liu and Hans van Ditmarsch

# Future work

- A practical approach for computing uniform interpolant;
- More general cases of common knowledge;
- Distributed knowledge;
- Progression and diagnose in multi-agent settings.



# Thank you!



Liangda Fang, Yongmei Liu and Hans van Ditmarsch

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